

Assignment V

1. Suppose a vector $v \in \mathbf{R}^3$ has coordinates $(1, 1, 1)$ w.r.t the basis $(1, 1, 0), (1, 0, 1), (0, 1, 1)$, Find its coordinates with respect to the basis $(1, 0, 0), (1, 1, 0), (1, 1, 1)$. Find the matrix of basis translation between these two bases. □
2. In all the questions below, V is a vector space over a field F of dimension n unless stated otherwise. Let U be a subspace of V of dimension k . Consider the cosets defined by U in V . (remember the work in all previous assignments!) Let $v_1 + U$ and $v_2 + U$ be cosets. We can define addition of cosets in a natural way as $(v_1 + U) + (v_2 + U) = (v_1 + v_2) + U$. Since vectors form a group with respect to addition, we have already shown that this operation is well defined. Define scalar multiplication of cosets also in the natural way $\alpha(v + U) = (\alpha v) + U$, for $\alpha \in F$ and $v \in V$. Show that if $v' = \alpha v$, then $v + U = v' + U$, establishing that multiplication defined this way also is well defined. With these operations, show that the set of cosets form a vector space. This space is called the *quotient space* defined by U in the vector space V denoted by V/U . □
3. In the previous question, Suppose u_1, u_2, \dots, u_k is a basis of U . Add vectors outside U to extend this set to a basis $u_1, u_2, \dots, u_k, b_1, b_2, \dots, b_r$ of V . (Clearly $r = n - k$ (why?); how do you do this extension systematically?). Show that in the quotient space V/U , $b_1 + U, b_2 + U, \dots, b_r + U$ are linearly independent. Show that they form a basis of V/U . Hence conclude that $\dim(V/U) = \dim(V) - \dim(U)$. □
4. In $V = \mathbf{R}^3$, consider the subspace U defined by the plane $x + y + z = 0$. what is dimension of V/U ? Find a vector $v \in V$ such that $u + W$ is a basis of V/U . Repeat the same question with U being replaced by the line defined by the intersection of the planes $x + y + z = 0$ and $z = 0$. □
5. Consider the linear map from \mathbf{R}^3 to \mathbf{R}^2 defined by $T(x_1, x_2, x_3) = (x_1 + x_2, x_2 + x_3)$. Find the matrix of this linear transformation if the basis on either side is the standard basis. What is the matrix of the map if the basis in \mathbf{R}^2 is changed to $(1, 1), (1, -1)$? What is the matrix when the basis for \mathbf{R}^3 is changed to $(1, 1, 0), (1, 0, 1), (0, 1, 1)$ and the basis of \mathbf{R}^2 is the standard basis? What is the matrix of the map if the basis for \mathbf{R}^3 is $(1, 1, 0), (1, 0, 1), (0, 1, 1)$ and basis for \mathbf{R}^2 is $(1, 1), (1, -1)$? □
6. In the above question, find the equations to $\text{img}(T)$ and $\text{ker}(T)$ (assume standard basis on both sides). Find a basis for $\text{ker}(T)$ and $\text{Img}(T)$. Find a collection of vectors in \mathbf{R}^3 whose images under T form a basis for $\text{img}(T)$. What is $\text{Rank}(T)$, $\text{Nullity}(T)$? □
7. Let T be a linear transformation from V to W over a field F . Let $\text{Dim}(V) = n, U = \text{Nullspace}(T)$. Let $\text{Nullity}(T) = k$ and $\text{rank}(T) = r$. Let u_1, u_2, \dots, u_k be a basis of U . Suppose we extend this set with vectors b_1, b_2, \dots, b_r to form a basis of V , is it always true that $T(b_1), T(b_2), \dots, T(b_r)$ forms a basis of $\text{Img}(T)$? Give a proof/counterexample. □
8. In the above question, Define the map $f : V/U \longrightarrow \text{Img}(T)$ as follows: $f(v + U) = T(v)$. □
 1. Show that f is well defined. That is, if $v + U = v' + U$ then $f(v + U) = f(v' + U)$.
 2. Show that f is a linear map from V/U to W .
 3. Show that f is injective; Hence conclude that f is an isomorphism between V/W and $\text{Img}(T)$. (This observation is called the first homomorphism theorem for vector spaces.) Conclude that $\text{Dim}(\text{Img}(T)) = \text{Dim}(V/W) = n - k$ (the last equality following from the the third question). This gives another proof for the Rank Nullity Theorem.