Summer School on Graph Theory and Graph Algorithms

- 1. Let S be a set of n line segments in the plane. Let k denote the number of intersection points among line segments in S. Assume that for every intersection point there are just two line segments of S that pass through it, and there is no pair of line segments that have more than a single point in common. We are interested in computing a shortest horizontal line segment that intersects at least three line segments of S and is as short as possible. Write down a plane sweep algorithm to solve this problem.
- 2. Is it possible to construct a point set with three sites whose Voronoi vertex is exterior to the triangle determined by the sites?
- 3. Prove that there is no algorithm that can compute the Voronoi diagram of n sites faster than nlogn in the worst case
- 4. The edges of both the Delaunay and Voronoi diagrams are line segments. Give a simple necessary and sufficient condition on a pair of sites A and B so that AB is a Delaunay edge and AB intersects its dual Voronoi edge.
- 5. Any set of points in the plane implicitly defines a weighted, complete graph whose vertices are the points themselves, whose edges are line segments, and where the weight of an edge is its Euclidean length. A Euclidean minimum spanning tree of a set of points is a minimum spanning tree of this graph. Prove that Euclidean minimum spanning tree is a subgraph of Delaunay triangulation.